

# WL-11001-2 UNDERWATER GPS G2



### **DESCRIPTION**

Underwater GPS G2 is the most robust acoustic positioning system on the market today.

The Topside with its internal positioning computer uses advanced algorithms to triangulate and calculate the position of the Locator based on the received signals from the Antenna/Receivers. Combined with the integrated GPS and IMU, it will provide the absolute GPS position of the Locator.

The Underwater GPS G2 system is running an internal webserver reachable through Wi-Fi exposing a GUI and a SW API

# **KEY FEATURES**

- Robust acoustic position, even in the most challenging areas like shallow water, inside tanks/pools, around installations etc.
- Fully omnidirectional with 360 degrees operational area.
- Fully flexible depth range where the Locator may be operated all the way up to just barely submerged.
- 100- and 300-meter range versions available.

- Choose between a flexible baseline using the separate Receivers or the quick-deploy Antenna for easy setup.
- On-board user-friendly web-based GUI with comprehensive diagnostic features.
- Open software API for integration.
- Small size enabling easy mounting and integration with other equipment.
- Wide range of interfaces enabling integration to other equipment.

## **EXTERNAL REQUIREMENTS**

To start using your Underwater GPS G2 kit, the only other requirements are:

- A power source (10-30V DC)
- PC/tablet/smartphone with a web browser to show the GUI



### **MECHANICAL**

Kit weight : ~ 4-6 kg

Housing ext. dimensions : 30 x 21 x 10 cm

(Pelican case)

Depth rating : 300 meters

Operating temperature : -10 to +60 °C

## ELECTRICAL / INTERFACE

Input voltage : 10-30 V

Power consumption : 0.25A at 12V

Power-on current surge : 2.30A at 12V

Communication : WiFi

(802.11ac/a/b/g/n)

: Ethernet (100 Mbps)

: NMEA 0183

Protocols : Water Linked API

User interface : Web based GUI

(local connection)

### ACOUSTIC / PERFORMANCE

Range : 100 or 300 meter radius

(depending on version)

Ping rate : 2-4 hz

Accuracy : Horizontal range : <0.2 %

Horizontal angle : <1 deg

Vertical (depth) : <1 %

Long term drift : Locator A1/D1: None

: Locator U1: ~1m/6h

Frequency: 31.25-250 kHz

(200 kHz typical)

Directivity : Omnidirectional

(360 degrees)

Operating principle : Time of flight,

Triangulation

Integrated IMUs : Yost Labs TSS-NANO

: TDK Invensense ICM-20948

Integrated GPS : u-blox NEO-M8T

# **APPROVALS**

CE

# **ORDERING GUIDE**



### **OPERATING PRINCIPLE**

# Antenna Receivers

### **TOPSIDE**

WL-21018 Pelican Case WL-21025 19" Rack Mount

### BASELINE

**1x WL-21027** Receiver-D1 (10/50/100m)

4x WL-21005 Antenna

### SOFTWARE

**WL-71002-R100** 100 meter range **WL-71002-R300** 300 meter range

### **LOCATOR**

**WL-21018** Locator-U1 **WL-21016** Locator-D1 **WL-21009** Locator-A1

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